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2 DOF ROBOT Www.makeblock.cc Lab Kit Ultimate Kit V1.1. Part List Beam 0824-144 Beam 0824-160 Plate 3x6 2x 1x 2x DC Motor-25 Countersunk Screw M3x8 DC Motor-25 Bracket 2x 6x Headless Screw M3x5 Shaft Connector-4 5x Timing Pulley 90T 2x 6x 3x Bracket 3x3 Flange Bearing 4x8x3mm Shaft Collar 4mm 3x Threaded Shaft 4x31mm 3x 6x 2th, 2024

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Makeblock Constructor I 3D Printer Kit 19 2.4.1 Wiring Four Stepper Motors Step1. Connect The X Motor To The Connector Labeled X. Ensure The Red Cable Is Closest To The Green Screw Terminals On The RAMPS Board (Wire Orders From Left To Right: Red, Blue, Green And Black). Note: If You Don't Wiring By Color Order, The Motor Motion Will Be Incorrect. 3th, 2024

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HID Usage Tables.pdf Attached Together With This Project. Power Supply For The Circuit Figure 9 This Project Differs With Previous PR, Where It Gets Power Supply From Computer Through USB Cable. From The Figure Above, Pwr Is Green LED To Indicate The Power Status Of The Circuit. The Power Led That Connected Between Vcc And GND Will Light On, If The 3th, 2024

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#define IMU\_SDA\_PIN 21 #define IMU\_SCL\_PIN 22 Using The IMU The IMU On The

Shield Is The LSM9DS1, Which Is Connected The The ESP32 Thing To The I2C Port Only. Any Of The Examples From The LSM9DS1 Library Should 3th, 2024

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